

# Bounded relative error and Vanishing relative error in Monte Carlo evaluation of static Network Reliability measures

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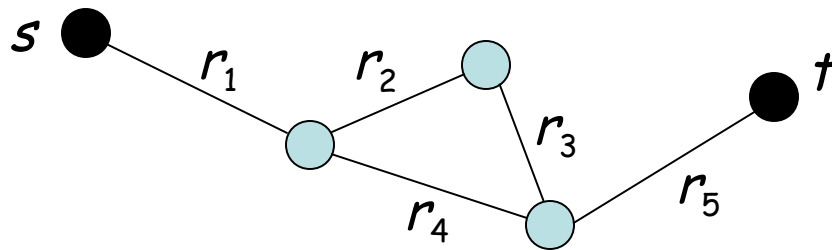
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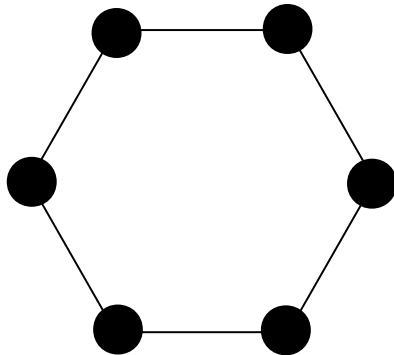
# AGENDA

- Classical network reliability model.
- Monte Carlo Simulation
- Variance Reduction methods
- Recursive Variance Reduction
- Asymptotic Zero Variance
- Conclusions

# 1 NETWORK RELIABILITY



$$R_{st} = r_1(r_2 r_3 + r_4 - r_2 r_3 r_4)r_5$$

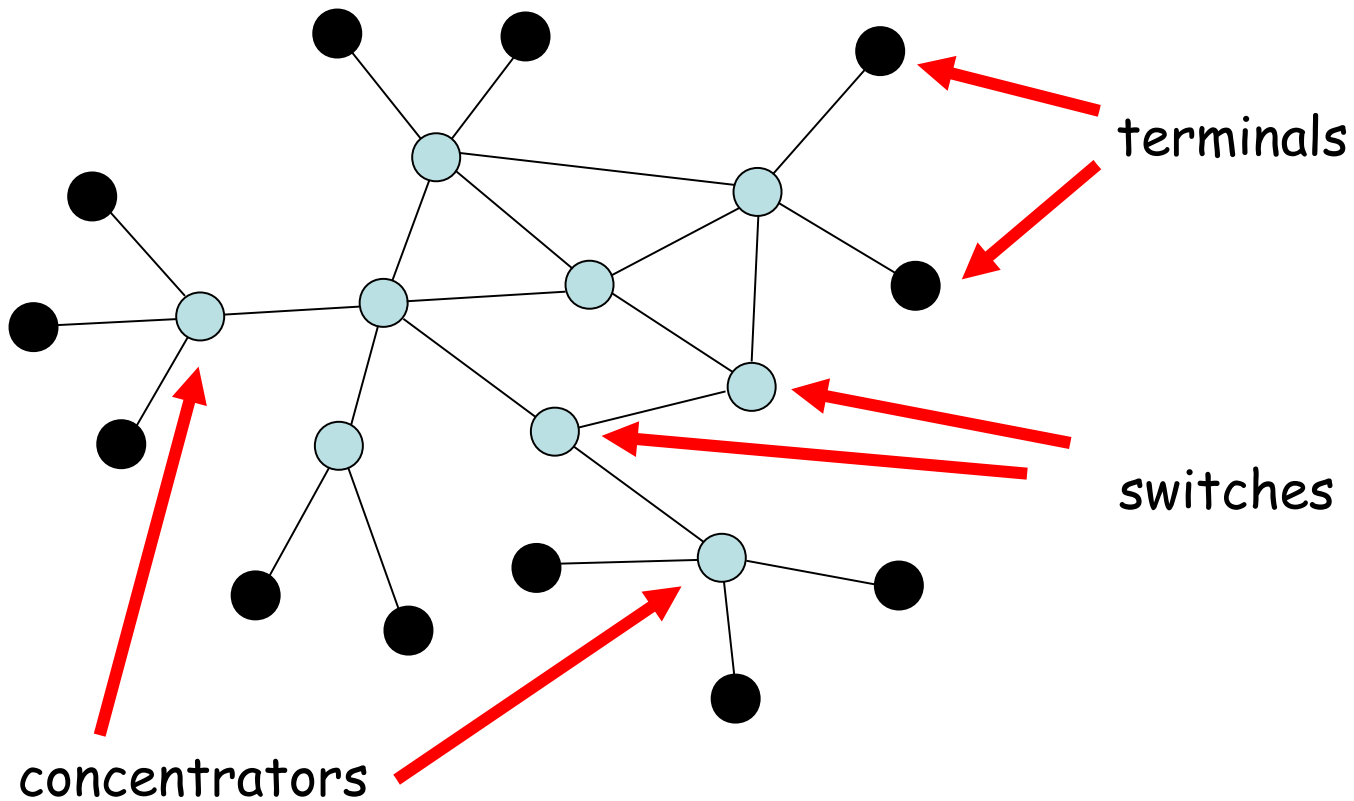


$$r_i = r$$

$$R_{\text{all}} = r^5(6 - 5r)$$

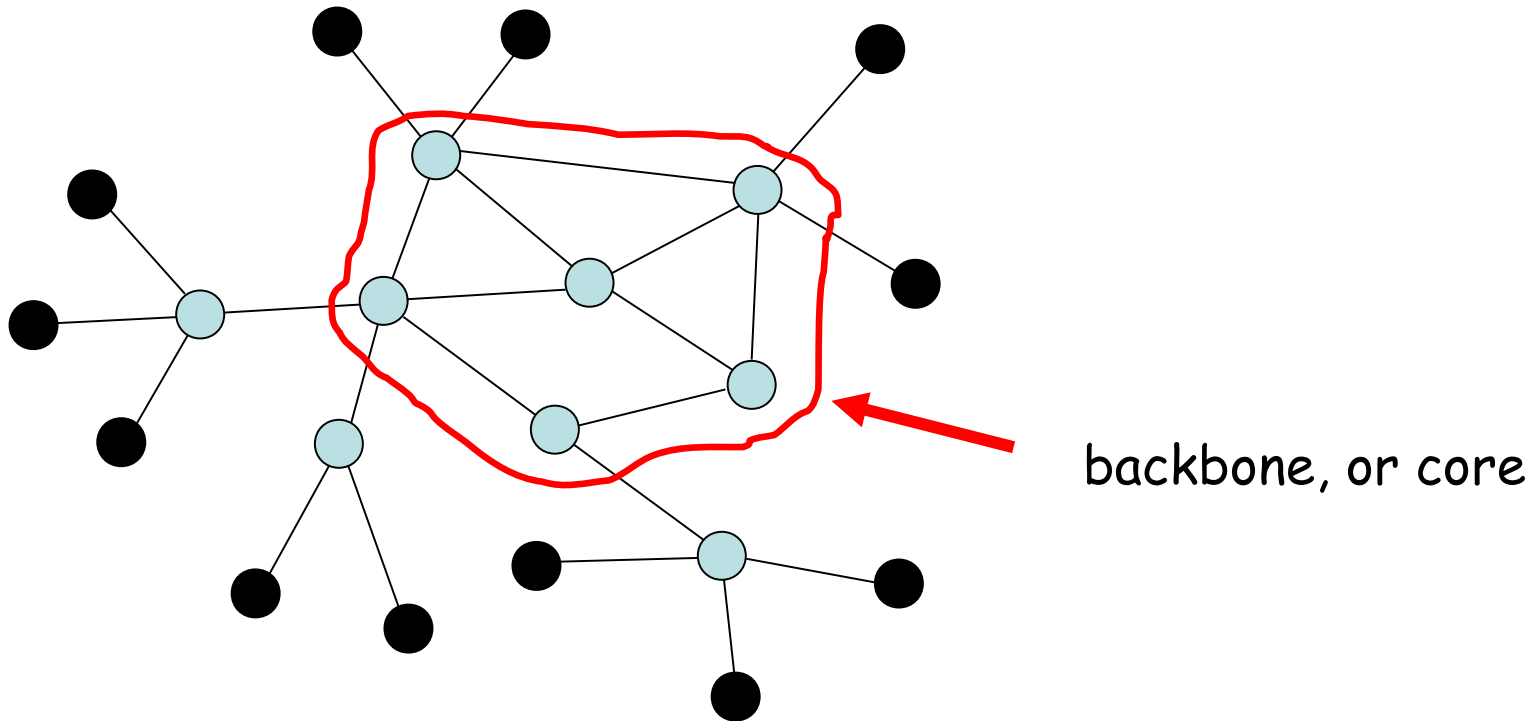
# REFERENCE MODEL

## A COMMUNICATION NETWORK



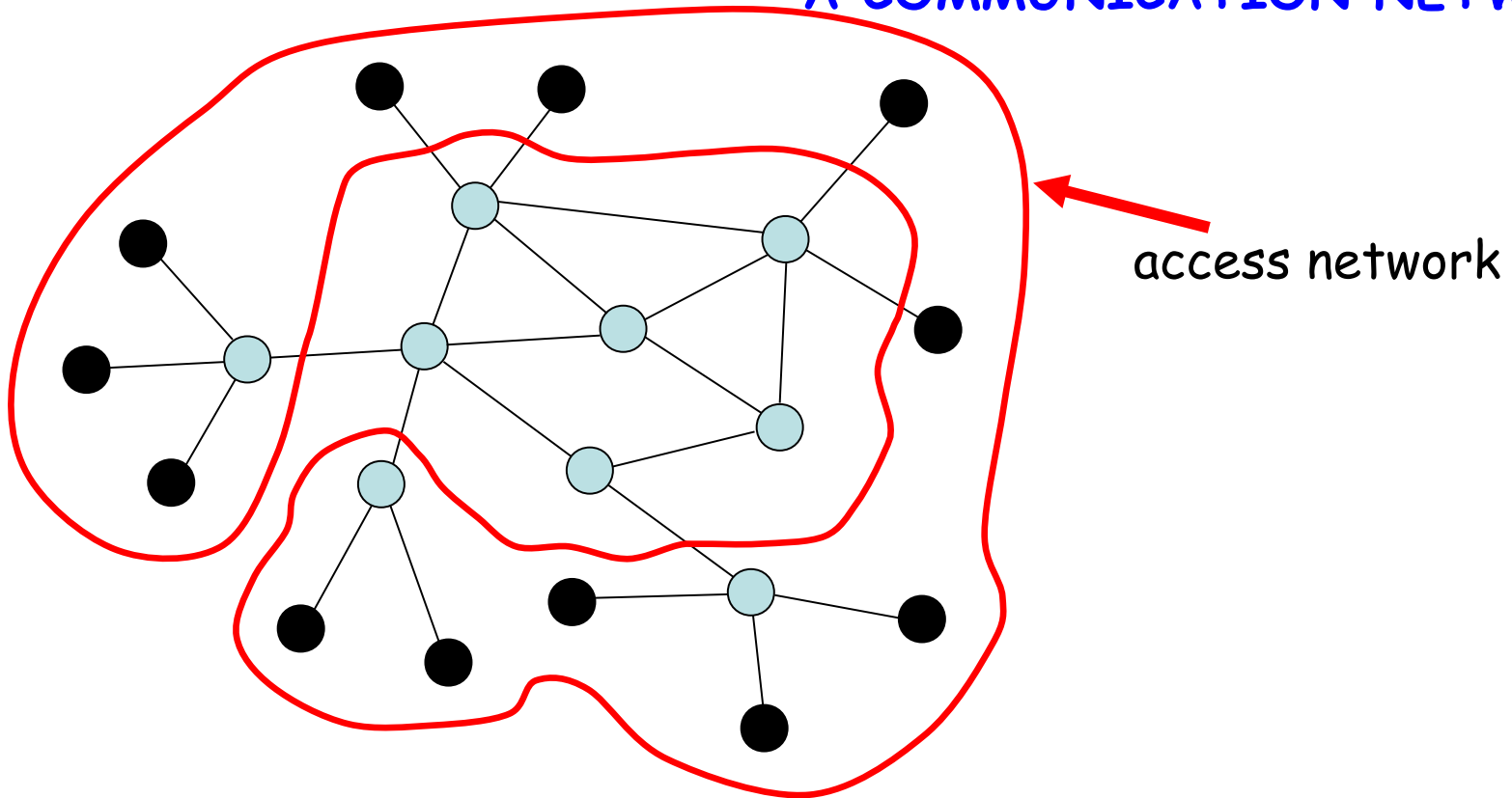
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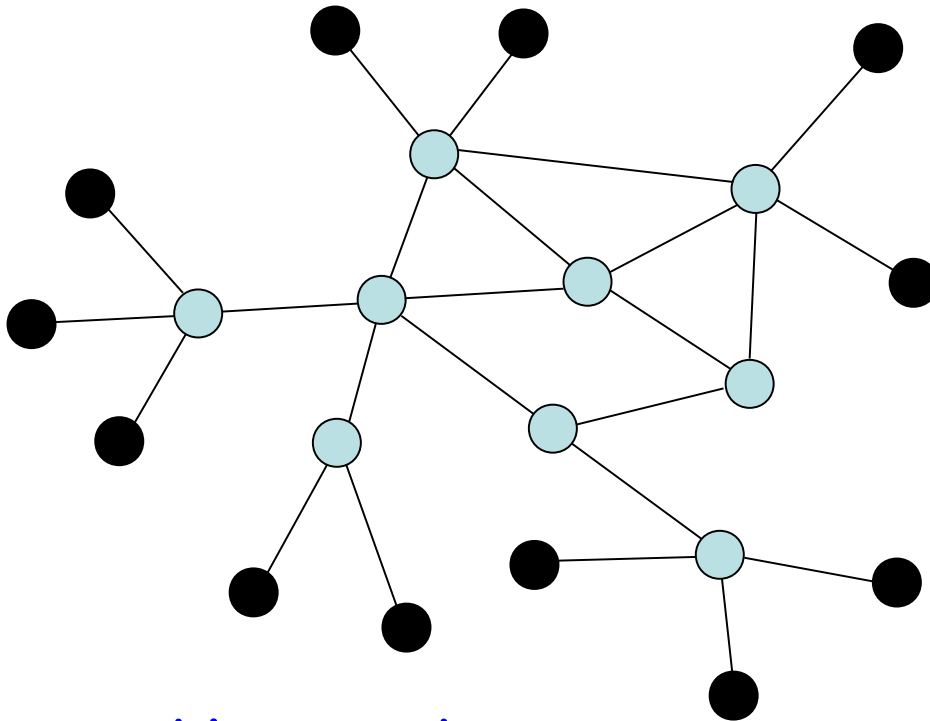


# REFERENCE MODEL

## A COMMUNICATION NETWORK



# REFERENCE MODEL



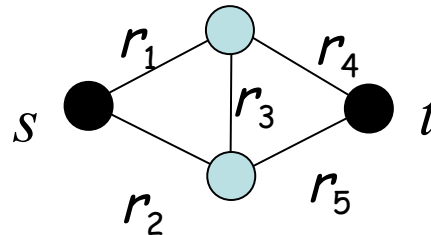
- nodes are perfect
- lines behave independently
- lines are up or down
- for each line  $i$ ,  
 $r_i = \text{Pr}(\text{line } i \text{ is up})$

Associated key-words:

- reliability diagrams, fault-trees...
- graph theory, coherent binary structure theory

# MATHEMATICAL MODEL

- $V$ : the nodes  
 $K$ : the *terminals*, or target-set,  $K \subseteq V$   
 $E$ : the *lines* or edges  
 $\{r_i\}_{i \in E}$ : the *elementary reliabilities*
- $N = (V, E)$ : (the underlying) undirected graph
- Simple example: the "bridge",  $K = \{s, t\}$



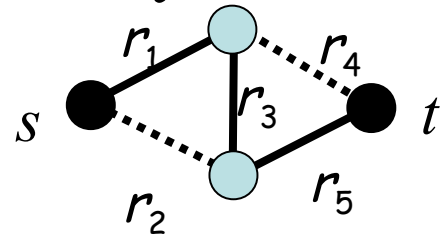


# PROBABILITY STRUCTURE

- $\Omega$ : set of all partial sub-graphs of  $N$  (same nodes, part of the edges)
- $G = (V, F)$ : a random graph on  $\Omega$ ;  
probabilistic structure:  
for any  $H \subseteq E$

$$\Pr(G = (V, H)) = \prod_{i \in H} r_i \prod_{j \notin H} (1 - r_j)$$

- Example:  $H = \{1, 3, 5\}$ ,  
 $\Pr(G = (V, H)) =$   
 $r_1 r_3 r_5 (1 - r_2) (1 - r_4)$



# RELIABILITY METRIC

- Goal:  $R = K$ -network reliability,  
=  $\Pr(\text{the nodes in } K \text{ are connected})$   
(or equivalently  $Q = 1 - R$ )
- $U$ : set of all partial sub-graphs of  $N$  where all nodes in  $K$  are connected; thus,  
 $R = \Pr(G \in U)$ .

# SERIES-PARALLEL REDUCTIONS

Series reduction:  $R \left[ \begin{array}{c} \bullet \xrightarrow{r_1} \text{light blue} \xrightarrow{r_2} \bullet \end{array} \right] = R \left[ \bullet \xrightarrow{r_1 r_2} \bullet \right]$

---

$R \left[ \begin{array}{c} \bullet \xrightarrow{r_1} \text{light blue} \xrightarrow{r_2} \text{light blue} \xrightarrow{r_3} \text{light blue} \xrightarrow{r_4} \text{light blue} \xrightarrow{r_5} \bullet \end{array} \right] = R \left[ \begin{array}{c} \bullet \xrightarrow{r_1} \text{light blue} \xrightarrow{r_2 r_3} \text{light blue} \xrightarrow{r_4} \text{light blue} \xrightarrow{r_5} \bullet \end{array} \right]$

Parallel reduction:  $R \left[ \begin{array}{c} \bullet \quad \bullet \\ \text{---} r_1 \text{---} \\ \text{---} r_2 \text{---} \end{array} \right] = R \left[ \begin{array}{c} \bullet \quad \bullet \\ \text{---} r_1 + r_2 - r_1 r_2 \text{---} \end{array} \right]$

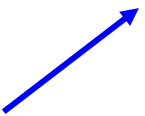
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$$R \left[ \begin{array}{c} \bullet \quad \bullet \quad \bullet \quad \bullet \\ \text{---} r_1 \text{---} \quad \text{---} r_2 \text{---} r_3 \text{---} \\ \quad \quad \text{---} r_4 \text{---} \end{array} \right] = R \left[ \begin{array}{c} \bullet \quad \bullet \quad \bullet \quad \bullet \\ \text{---} r_1 \text{---} \quad \text{---} r_2 r_3 + r_4 - r_2 r_3 r_4 \text{---} \\ \quad \quad \text{---} r_5 \text{---} \end{array} \right]$$

$r_2 r_3 + r_4 - r_2 r_3 r_4$

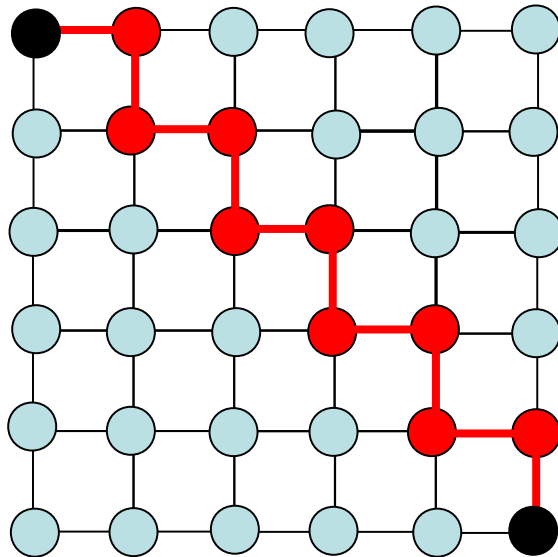
$$R \left[ \begin{array}{c} \bullet \xrightarrow{r_1} \circ \xrightarrow{r_2} \bullet \end{array} \right] = R \left[ \bullet \xrightarrow{r_1 r_2} \bullet \right]$$

$$R \left[ \begin{array}{c} \bullet \xrightarrow{r_1} \circ \xrightarrow{\quad} \circ \xrightarrow{r_5} \bullet \end{array} \right] = r_1 (r_2 r_3 + r_4 - r_2 r_3 r_4) r_5$$

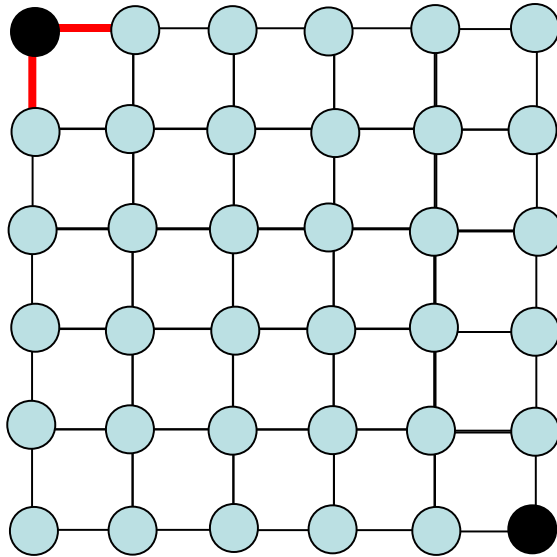
$r_2 r_3 + r_4 - r_2 r_3 r_4$ 


Series-parallel reductions have polynomial cost, but they are not always applicable (f.e, the “bridge” can not be reduced).

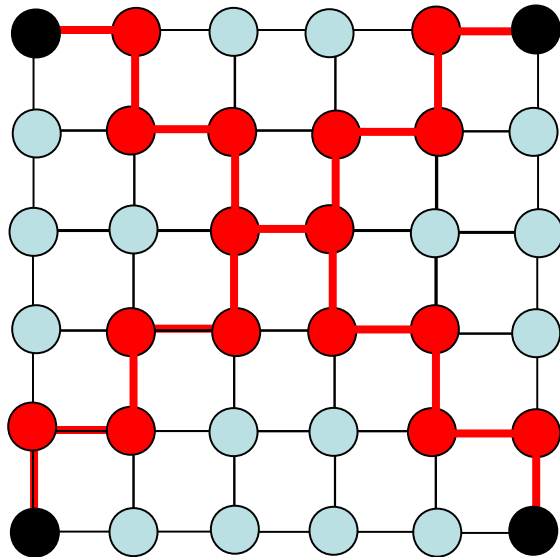
# PATHSETS AND CUTSETS



A minimal pathset, or  
*minpath* ( $|K| = 2$ )

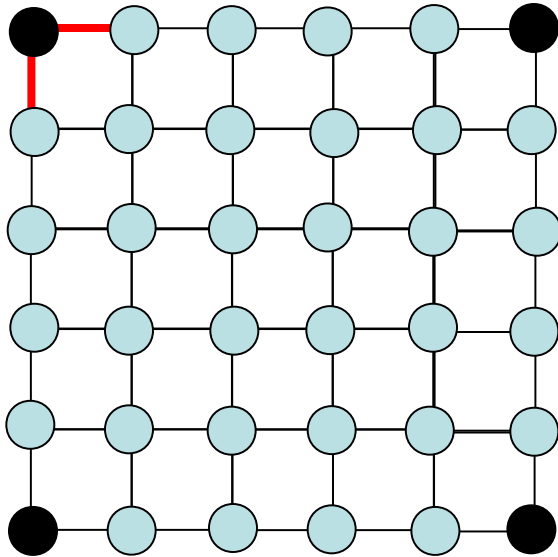


*A minimal cutset, or  
mincut ( $|K| = 2$ )*



*A minpath ( $|K| = 4$ )*





*A mincut ( $|K| = 4$ )*

- Let  $P$  be a pathset.
- Let  $P$ -up denote the event  
 $P$ -up = "all links in  $P$  are up",  
 $\Pr(P\text{-up}) = \prod_{\text{link } i \text{ is in } P} r_i$
- Since  $P\text{-up} \Rightarrow \text{system is up}$ ,  
 $\Pr(P\text{-up}) \leq R$
- Let  $C$  be a cutset.
- Let  $C$ -down denote the event  
 $C$ -down = "all links in  $C$  are down",  
 $\Pr(C\text{-down}) = \prod_{\text{link } i \text{ is in } C} (1 - r_i)$
- Since  $C\text{-down} \Rightarrow \text{system is down}$ ,  
 $\Pr(C\text{-down}) \leq Q = 1 - R$

# EXACT EVALUATION

- Computational complexity
  - General case : #P-hard.
  - For  $K=\{s,t\}$  : #P-hard
  - For  $K=V$ : #P-hard
  - #P-hard for planar graphs.
  - Polynomial complexity for s-p reducible networks
  - Polynomial complexity for complete topologies and equireliable links, and  $K=\{s,t\}$ .

# OTHER ALTERNATIVES TO EXACT EVALUATION

- Upper and lower bounds
  - Can be used in place of exact results, for evaluating or designing a network.
  - Should be tight and computed efficiently
- Monte Carlo simulation.
  - Computational complexity grows moderately with network size (usually linearly or quadratically).
  - Compromise between precision and computation time.
  - Precision depends on value of edge reliabilities; problems when the reliabilities are very small (rare event situation).

# AGENDA

- Classical network reliability model.
- Monte Carlo Simulation
- Variance Reduction methods
- Recursive Variance Reduction
- Splitting
- Conclusions

# STANDARD MONTE CARLO SIMULATION

- $\#failed = 0$
- **for**  $m = 1, 2, \dots, M$ 
  - $g = \text{sample}(G)$
  - **if**  $g \notin U$  **then**  $\#failed += 1$
- $Q^{std} = \#failed / M$
- $V^{std} = Q^{std} (1 - Q^{std}) / (M-1)$

- $M$  - sample size
- $Q^{std}$  - unreliability estimator
- $V^{std}$  - estimator of the variance of  $Q^{std}$

# COMPUTATIONAL COMPLEXITY

- Internal loop: sampling a graph state (state of each edge), and verify if belongs or not to set  $U$  (DFS search); total complexity of order  $O(|E|)$ .
- $M$  iterations; initialization time and final computations of  $O(1)$ .
- Total computation time  $O(M|E|)$ , linear in nb. of edges and nb. of replications.

# PRECISION

- Relative error estimation:

$$\begin{aligned}\text{RelErr} &= (V^{\text{std}})^{1/2} / Q^{\text{std}} \\ &= [(1 - Q^{\text{std}}) Q^{\text{std}} / (M-1)]^{1/2} / Q^{\text{std}}\end{aligned}$$

$$\begin{aligned}&= [(1 - Q^{\text{std}}) / ((M-1) Q^{\text{std}})]^{1/2} \\ &\approx 1 / (M Q^{\text{std}})^{1/2}\end{aligned}$$

- When  $Q \ll 1$ , relative error grows, and if  $Q \rightarrow 0$ ,  $\text{RelErr} \rightarrow \infty$  (Rare Event problem).
- Error does not depend on the network size, but depends on edge reliability; if high reliabilities, a failure of the network has very low probability to be observed (rare event).



- It is possible to improve precision, taking more replications. To obtain a relative error relativo RelErr, we can compute  $M$  from the previous formula, obtaining  $M \approx 1/(Q(\text{RelErr})^2)$ .
- Total computation time of order  $O(M |E|)$ ; when  $Q$  or RelErr very small, it will be prohibitively large  $\Rightarrow$  motivation to develop variants improving the behavior of standard Monte Carlo ("Variance reduction methods").

# VARIANCE REDUCTION METHODS

- Generic methods, applicable to any simulation problem:
  - Importance sampling; cross-entropy.
  - Antithetic variates.
  - Control variates.
  - Stratified sampling.
- Specific for network reliability:
  - Employ structure and properties of the reliability problem to improve variance or computation time.
  - Many times adapt ideas from generic methods and from exact computation methods.

- Many ideas and methods in literature.
- A high level classification:
  - Based on bounds on the reliability (sampling in a subset of  $\Omega$  , which lowers the variance). Van Slyke and Frank/ Kumamoto, Tanaka and Inoue / Fishman.
  - Based on antithetic sampling or generalizations (improve efficiency in generation of uniform variates and lowers the variance). Kumamoto, Tanaka and Inoue / Rubino and El Khadiri / Wei-Chang Yeh .
  - Based on partitioning state space  $\Omega$ . , or on reformulating the problem in terms of other random variables with smaller variance. Karp and Luby / Jun and Ross / Cancela and El Khadiri.

- Based on graph evolution models (stochastic processes), with importance sampling to reduce variance. Wong and Easton / Elperin, Gertsbakh and Lomonosov.
- Cross-Entropy based variants to optimize the IS parameters. Hui, Bean, Kraetzl, and Kroese.
- Reformulations of the standard method to improve the computational efficiency. Rubino and El Khadiri.

# ALTERNATIVES FOR METHOD EVALUATION

- Computational studies over test sets.
- Study of theoretical properties and asymptotic behavior.

# COMPUTATIONAL STUDIES

- Over test sets, comprising different topologies and reliabilities.
- Problems:
  - Absence of standardized test library.
  - Unavailability of methods' implementations..
  - Literature results which only include variances, not running times.
  - Difficulties in normalizing running times over different computers.

- Performance measures for a method  $x$ :
  - Variance  $\text{Var}(Q^x)$ , for a fixed sample size  $M$ , or for a given time  $T$ .
  - Computation time  $T(Q^m)$ , for a fixed sample size  $M$ , or to obtain a predetermined precision.
  - Comparison against a reference method, standard Monte Carlo.

- How to compute the "speedup" of method  $x$  w.r.t. method  $y$ ?
  - Fixed  $M$ , variance ratio  $\text{Var}(Q^y) / \text{Var}(Q^x)$ .  
Problem: does not take into account computing time per iteration.
  - More fair alternative:
    - Fix the precision
    - Run until obtaining this precision, compute
    - $T(Q^y) / T(Q^x)$ .
  - Problem: if computing times differ by many orders of magnitude, unfeasible (example: if  $T(Q^y) / T(Q^x) = 10^9$ , and  $T(Q^x) = 1$  sec,  $T(Q^y) = 31$  years).



- A better alternative
  - Relative efficiency (or speedup)  
 $\text{Var}(Q^y)T(Q^y)/\text{Var}(Q^x)T(Q^x)$ .
  - Interpretation:  
if  $\text{Var}(Q^y)T(Q^y)/\text{Var}(Q^x)T(Q^x) = W$ , then  
"method x is  $W$  times faster than method y "  
(i.e, it obtains the same precision with  $W$  times smaller effort).
  - Alternatively, for a given computational effort, method x obtains a variance  $W$  times smaller than method y.

# THEORETICAL STUDIES

- Direct comparison of variance, or upper bound of variance, to the standard Monte Carlo one.
- Asymptotic properties:
  - Bounded relative error.
  - Bounded normal approximation
  - Bounded relative efficiency.

# BOUNDED RELATIVE ERROR

- Framework:
  - $\varepsilon$  rarity parameter
  - Link reliability :  $r_i = 1 - a_i \varepsilon^{b_i}$
  - $Q(\varepsilon) \rightarrow 0$  when  $\varepsilon \rightarrow 0$ .
  - Relative error of method  $x$ :  $\text{RelErr} = (V^x)^{1/2} / Q$
- Definition:  
 $x$  verifies "Bounded relative error" iff for every network  $G$ , and every fixed  $M$ , there is  $E$  such that  $(V^x)^{1/2} / Q < E$  when  $\varepsilon \rightarrow 0$ .
- Interpretation: for a given topology and  $M$ , method  $x$  precision does not depend on  $\varepsilon$ .

# VANISHING RELATIVE ERROR

- Framework:
  - $\varepsilon$  rarity parameter
  - Link reliability :  $r_i = 1 - a_i \varepsilon^{b_i}$
  - $Q(\varepsilon) \rightarrow 0$  when  $\varepsilon \rightarrow 0$ .
  - Relative error of method x:  $\text{RelErr} = (V^x)^{1/2} / Q$
- Definition:  
x verifies "Vanishing relative error" iff for every network  $G$ , and every fixed  $M$ , there is  $E$  such that  $(V^x)^{1/2} / Q \rightarrow 0$  when  $\varepsilon \rightarrow 0$ .
- Interpretation: for a given topology and  $M$ , method precision improves for rare event cases.

# BOUNDED NORMAL APPROXIMATION

- Definition:  
x verifies "Bounded normal approximation" iff for every  $G$ , the distance between distribution of  $Q^x$  and a normal distribution is bounded when  $\varepsilon \rightarrow 0$  (this condition can be expressed using the third moment of  $Q^x$  and the variance, employing Berry-Essen theorem).
- Interpretation: employing  $Q^x$  and  $V^x$  it is possible to build an interval confidence based on the normal law, valid independently of  $\varepsilon$ .

# BOUNDED RELATIVE EFFICIENCY

- Definition:  
x verifies "Bounded relative efficiency" iff for every network  $G$ , and fixed  $M$ , there exists  $E$  s.t.  $Q^2 / (V^x T^x) > E$  when  $\varepsilon \rightarrow 0$ .
- Interpretation: given a topology, it is possible to obtain the same precision in the same computing time even when  $\varepsilon \rightarrow 0$  (the method is robust w.r.t. "rare events").

# Bounded relative error and Vanishing relative error in Monte Carlo evaluation of static Network Reliability measures (part 2)

H. Cancela

Universidad de la República

SBPO 2010, Bentos Gonçalves, September 2010

# Outline

- 1 Crude Monte Carlo simulation
  - Crude estimator
  - Rarity and associated problems
- 2 Recursive Variance Reduction (RVR) algorithm
  - Description
  - Relative error analysis
- 3 Balanced RVR
  - Description
  - Relative error analysis
- 4 Zero-variance Approximation RVR
- 5 Numerical results
- 6 Conclusions



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# Crude Monte Carlo simulation

- Random state-**vector** of the network:

$$X = (X_1, \dots, X_m)$$

where  $X_e$  Bernoulli r.v. = 1 if link  $e$  is working, 0 otherwise.

- Structure function  $\Phi$  of  $\{0, 1\}^m$  into  $\{0, 1\}$  such that  $\Phi(x) = 1$  if all nodes in  $\mathcal{K}$  are connected when the state-vector is  $x = (x_1, \dots, x_m)$ , and  $\Phi(x) = 0$  otherwise.
- Searched reliability:  $\mathbb{E}[\Phi(X)] = r = r(\mathcal{G})$  and unreliability  $q = 1 - r = \mathbb{E}[1 - \Phi(X)]$ .

# Crude Monte Carlo simulation

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- Searched reliability:  $\mathbb{E}[\Phi(X)] = r = r(\mathcal{G})$  and unreliability  $q = 1 - r = \mathbb{E}[1 - \Phi(X)]$ .
- Consider  $n$  independent copies  $X^{(i)} = (X_1^{(i)}, \dots, X_m^{(i)})$  of  $X$ , and compute  $Y^{(i)} = 1 - \Phi(X^{(i)})$ .
- The crude estimator of  $q$  is then

$$\hat{Y}_n = \frac{1}{n} \sum_{i=1}^n Y^{(i)}.$$

- Confidence interval built from the central limit theorem.

## Rarity modeling

- We assume that  $q = \mathbb{E}[Y] \ll 1$ .
- This can be due to the large number of paths connecting nodes in  $\mathcal{K}$  or to large reliabilities of individual links.
- We assume  $q_e \rightarrow 0 \ \forall e$ , so that  $q \rightarrow 0$ .
- The *relative error* is proportional to

$$\frac{\sqrt{\text{Var}[\hat{Y}_n]}}{\mathbb{E}[Y]} = \frac{\sqrt{q(1-q)}}{q\sqrt{n-1}} \rightarrow \infty$$

as  $q \rightarrow 0$ .

- As a consequence, more and more paths are required to get a specified relative error as  $q \rightarrow 0$ .

### Definition

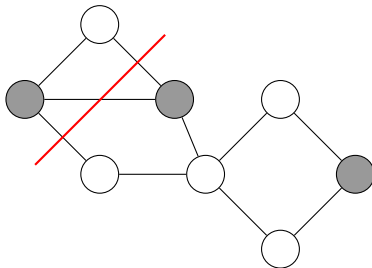
An estimator  $\hat{Y}'_n$  is said to verify *Bounded Relative Error (BRE)* if  $\frac{\sqrt{\text{Var}[\hat{Y}'_n]}}{\mathbb{E}[Y]}$  is bounded as  $\mathbb{E}[Y] \rightarrow 0$ . Equivalently, if  $\frac{\sqrt{\mathbb{E}[(\hat{Y}'_n)^2]}}{\mathbb{E}[Y]}$  is bounded as  $\mathbb{E}[Y] \rightarrow 0$ .

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# Recursive Variance Reduction (RVR)

- Principle: select a  $\mathcal{K}$ -cutset, i.e., a set  $\mathcal{C}$  of links whose failure ensures the system failure.



- If all links in  $\mathcal{C}$  are failed (probability  $q_{\mathcal{C}}$ ), the system is failed. Clearly,  $q_{\mathcal{C}} \leq q$ .
- $B_j$  = “the  $j - 1$  first links of  $\mathcal{C}$  are down, but the  $j$ -th is up”
- $\mathbb{P}[B_j] = (\prod_{k=1}^{j-1} q_k) r_j$
- Define  $p_j = \mathbb{P}[B_j \mid \text{at least one link is working}] = \mathbb{P}[B_j]/(1 - q_{\mathcal{C}})$

# Recursive Variance Reduction (RVR)

The RVR estimator:

- Select a cut, and compute  $q_C$  and the  $p_j$ s.
- Pick an edge at random in  $C$  according to the probability distribution  $(p_j)_{j=1, \dots, |C|}$
- Let the chosen edge be the  $j$ th. Call  $\mathcal{G}_j$  the graph obtained from  $\mathcal{G}$  by deleting the first  $j - 1$  edges of  $C$  and by contracting the  $j$ th.
- The value  $y_{RVR}$  returned by the RVR estimator of  $q(\mathcal{G})$ , the unreliability of  $\mathcal{G}$ , is recursively defined as

$$y_{RVR}(\mathcal{G}) = q_C + (1 - q_C)y_{RVR}(\mathcal{G}_j).$$

## RVR estimator

Formally, the RVR estimator of  $Q(\mathcal{G})$  is the random variable

$$Y_{RVR} = q_C + (1 - q_C) \sum_{j=1}^{|\mathcal{C}|} \frac{\mathbf{1}_{B_j}}{1 - q_C} Y_{RVR}(\mathcal{G}_j).$$

### Theorem

*The estimator is unbiased:  $\mathbb{E}[Y_{RVR}] = q(\mathcal{G}) = q$ .*

*Second moment computed as*

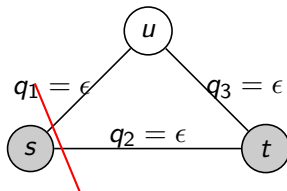
$$\begin{aligned} \mathbb{E}[Y_{RVR}^2] &= q_C^2 + 2q_C(1 - q_C) \left( \sum_{j=1}^{|\mathcal{C}|} \frac{\mathbb{P}[B_j]}{1 - q_C} \mathbb{E}[Y_{RVR}(\mathcal{G}_j)] \right) \\ &\quad + (1 - q_C)^2 \left( \sum_{j=1}^{|\mathcal{C}|} \frac{\mathbb{P}[B_j]}{1 - q_C} \mathbb{E}[Y_{RVR}^2(\mathcal{G}_j)] \right). \end{aligned}$$



# No Bounded Relative Error for RVR

## Proposition

*RVR algorithm does not verify Bounded Relative Error property.*



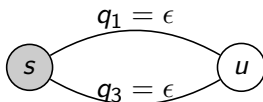
- Cut: the two links starting from node  $s$  and ordering them as first [the link from  \$s\$  to  \$t\$](#) .
- $q_C = \epsilon^2$ .

$$\begin{aligned}\mathbb{E}[Y_{RVR}^2] &= \epsilon^4 + 2\epsilon^2 \left[ (1 - \epsilon)\mathbb{E}[Y_{RVR}(\mathcal{G}_1)] + \epsilon(1 - \epsilon)\mathbb{E}[Y_{RVR}(\mathcal{G}_2)] \right] \\ &+ (1 - \epsilon^2) \left[ (1 - \epsilon)\mathbb{E}[Y_{RVR}^2(\mathcal{G}_1)] + \epsilon(1 - \epsilon)\mathbb{E}[Y_{RVR}^2(\mathcal{G}_2)] \right].\end{aligned}$$

## Counter-example for BRE (ctd)

where

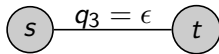
- $\mathcal{G}_1$ : link from  $s$  to  $t$  is working  $\rightsquigarrow s$  and  $t$  are merged (the system is



necessarily connected).

$Y_{RVR}(\mathcal{G}_1) = 0$ . Thus  $\mathbb{E}[Y_{RVR}(\mathcal{G}_1)] = \mathbb{E}[Y_{RVR}^2(\mathcal{G}_1)] = 0$ .

- $\mathcal{G}_2$ : link from  $s$  to  $t$  failed, but the one from  $s$  to  $u$  is working  $\rightsquigarrow s$



and  $u$  are merged.

$\mathbb{E}[Y_{RVR}(\mathcal{G}_2)] = \epsilon$ ,  $\mathbb{E}[Y_{RVR}^2(\mathcal{G}_2)] = \epsilon^2$ .

- Finally,  $\mathbb{E}[Y_{RVR}^2] = \Theta(\epsilon^3)$ , and  $\mathbb{E}[Y_{RVR}^2]/(\mathbb{E}[Y_{RVR}])^2 = \Theta(\epsilon^{-1}) \rightarrow \infty$  as  $\epsilon \rightarrow 0$ .

We may have BRE depending on the ordering of the links.

# Outline

- 1 Crude Monte Carlo simulation
  - Crude estimator
  - Rarity and associated problems
- 2 Recursive Variance Reduction (RVR) algorithm
  - Description
  - Relative error analysis
- 3 **Balanced RVR**
  - Description
  - Relative error analysis
- 4 Zero-variance Approximation RVR
- 5 Numerical results
- 6 Conclusions

## Balanced RVR

- Non-BRE comes from the crude distribution for sampling the first working link on the cut.
- *Importance Sampling (IS)* used instead; that is, the sampling of the first line up in the cut is not anymore  $(p_j)$ .
- So far, we built a partition by assigning to the events  $B_j$ , for  $1 \leq j \leq |\mathcal{C}|$ , the conditional probabilities

$$p_j = \mathbb{P}[B_j | A],$$

where  $A$  is the event “at least one link in cut  $\mathcal{C}$  is up”.

- Let us write the RVR estimator as

$$Y_{RVR} = q_{\mathcal{C}} + (1 - q_{\mathcal{C}}) \sum_{j=1}^{|\mathcal{C}|} \mathbf{1}_{B'_j} Y_{RVR}(\mathcal{G}_j),$$

where  $B'_j$  represents the same event as  $B_j$  but has the (conditional) probability  $p_j$ .

# Balanced RVR

- Now, we change this probability  $p_j$  by the uniform distribution on  $\{1, 2, \dots, |\mathcal{C}|\}$ ,  $\tilde{p}_j = 1/|\mathcal{C}|$ , for sampling  $B'_j$ .
- Let us call  $Y_{BRVR}$  the corresponding estimator, but using this uniform distribution, we write

$$\begin{aligned} Y_{BRVR} &= q_{\mathcal{C}} + (1 - q_{\mathcal{C}}) \sum_{j=1}^{|\mathcal{C}|} \mathbf{1}_{B'_j} \frac{p_j}{\tilde{p}_j} Y_{BRVR}(\mathcal{G}_j) \\ &= q_{\mathcal{C}} + |\mathcal{C}| \sum_{j=1}^{|\mathcal{C}|} \mathbf{1}_{B'_j} \mathbb{P}[B_j] Y_{BRVR}(\mathcal{G}_j). \end{aligned}$$

- Estimator: using likelihood ratio  $p_j/\tilde{p}_j$  to keep it unbiased.

# Results on Balanced RVR

## Theorem

*The estimator  $Y_{BRVR}$  is unbiased:  $\mathbb{E}[Y_{BRVR}] = q$ .  
BRVR algorithm verifies Bounded Relative Error property.*

Proof by induction from

$$\begin{aligned}\mathbb{E}[Y_{BRVR}^2] &= q_C^2 + 2q_C|C| \left( \sum_{j=1}^{|C|} \mathbb{P}[B_j] \mathbb{E}[Y_{BRVR}(\mathcal{G}_j)] \right) \\ &\quad + |C|^2 \left( \sum_{j=1}^{|C|} (\mathbb{P}[B_j])^2 \mathbb{E}[Y_{BRVR}^2(\mathcal{G}_j)] \right).\end{aligned}$$

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- 6 Conclusions

## Zero-variance Approximation RVR

- *Zero-variance change of measure*: chooses the appropriate (ideally the best) IS for the first working link on the cut:
- choose  $B'_j$  with probability  $\tilde{p}_j$  in the IS estimator, with

$$\tilde{p}_j = \frac{\mathbb{P}[B_j]q(\mathcal{G}_j)}{\sum_{k=1}^{|\mathcal{C}|} \mathbb{P}[B_k]q(\mathcal{G}_k)} \quad (1)$$

- Resulting estimator:

$$Y_{ZVR} = q_{\mathcal{C}} + \left( \sum_{k=1}^{|\mathcal{C}|} \mathbb{P}[B_k]q(\mathcal{G}_k) \right) \sum_{j=1}^{|\mathcal{C}|} \mathbf{1}_{B'_j(\mathcal{G})} \frac{1}{q(\mathcal{G}_j)} Y_{ZVR}(\mathcal{G}_j).$$

### Theorem

$Y_{ZVR}$  has variance  $\text{Var}[Y_{ZVR}] = 0$ .

- Implementing it requires the knowledge of the  $q(\mathcal{G}_i)$ , but in that case, no need to simulate!



# Zero Variance Approximation

- Instead, use **some** approximation  $\hat{q}(\mathcal{G}_i)$  of  $q(\mathcal{G}_i)$  plugged into (1).

$$Y_{AZRVR} = q_C + \left( \sum_{k=1}^{|\mathcal{C}|} \mathbb{P}[B_k] \hat{q}(\mathcal{G}_k) \right) \sum_{j=1}^{|\mathcal{C}|} \mathbf{1}_{B'_j(\mathcal{G})} \frac{1}{\hat{q}(\mathcal{G}_j)} Y_{AZRVR}(\mathcal{G}_j).$$

## Proposition

If  $\forall 1 \leq j \leq |\mathcal{C}|$ ,  $\hat{q}(\mathcal{G}_j) = \Theta(q(\mathcal{G}_j))$  as  $\epsilon \rightarrow 0$ ,  $Y_{AZRVR}$  verifies BRE property.

# Zero Variance Approximation

- Define the *mincut-maxprob* approximation  $\hat{q}(\mathcal{G})$  of  $q(\mathcal{G})$  as maximal probability of a mincut of graph  $\mathcal{G}$  (computed in polynomial time).

## Proposition

*With the mincut-maxprob approximation,  $\hat{q}(\mathcal{G}_j) = \Theta(q(\mathcal{G}_j))$  as  $\epsilon \rightarrow 0$ , therefore BRE property is obtained.*

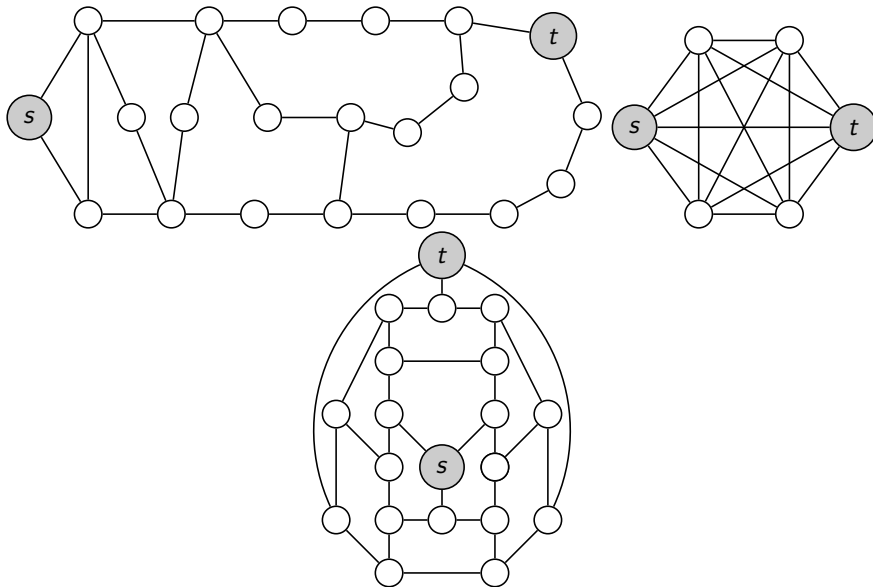
## Proposition

*If,  $\hat{q}(\mathcal{G}_j) = q(\mathcal{G}_j) + o(q(\mathcal{G}_j))$  as  $\epsilon \rightarrow 0$  for all  $1 \leq j \leq |\mathcal{C}|$ , the Vanishing relative (VRE) property (the RE tends to 0, **stronger than just** being bounded) is verified.*

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  - Description
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# Three topologies: arpanet, C6, dodecahedron



Network ( $q_e$ )	$Q(G)$	$N \times \text{Var}(SMC)$	$N \times \text{Var}(RVR)$	$N \times \text{Var}(Bal)$	$N \times \text{Var}(AZV)$
Arp (5.00 e-01)	9.63989 e-01	3.47133 e-02	3.71795 e-03	1.60608 e-01	1.69321 e-01
Arp (3.00 e-01)	6.81507 e-01	2.17055 e-01	4.74801 e-02	5.65742 e-01	8.45549 e-01
Arp (1.00 e-01)	9.54229 e-02	8.63174 e-02	1.46865 e-02	3.68529 e-02	9.55806 e-02
Arp (1.00 e-02)	6.54074 e-04	6.53646 e-04	1.63753 e-05	6.71095 e-07	3.06912 e-06
Arp (1.00 e-03)	6.05581 e-06	6.05577 e-06	1.60407 e-08	5.64473 e-11	3.43246 e-11
Arp (1.00 e-04)	6.00560 e-08	6.00560 e-08	1.60041 e-11	5.69261 e-15	3.47090 e-16
Arp (1.00 e-05)	6.00056 e-10	6.00056 e-10	1.60004 e-14	5.69924 e-19	3.47477 e-21
Arp (1.00 e-06)	6.00006 e-12	6.00006 e-12	1.60000 e-17	5.69992 e-23	3.47512 e-26
C6 (5.00 e-01)	7.64160 e-02	7.05766 e-02	7.72612 e-05	6.87599 e-4	7.27858 e-05
C6 (3.00 e-01)	5.26728 e-03	5.23953 e-03	2.56429 e-07	7.86630 e-06	2.27577 e-07
C6 (1.00 e-01)	2.00766 e-05	2.00762 e-05	1.28070 e-13	2.28489 e-10	1.17223 e-13
C6 (1.00 e-02)	2.00001 e-10	2.00001 e-10	1.01244 e-26	2.92080 e-20	1.00225 e-26
C6 (1.00 e-03)	2.00000 e-15	2.00000 e-15	1.00102 e-39	2.99201 e-30	1.00002 e-039
C6 (1.00 e-04)	2.00000 e-20	2.00000 e-20	1.00000 e-52	2.99920 e-40	1.00000 e-52
C6 (1.00 e-05)	2.00000 e-25	2.00000 e-25	1.42434 e-65	2.99992 e-50	1.42434 e-65
C6 (1.00 e-06)	1.99998 e-30	1.99998 e-30	num. pblm.	2.99986 e-60	num. pblm.
Dod (5.00 e-01)	7.09745 e-01	2.06007 e-01	1.57246 e-02	4.23225 e-01	1.34634 e-01
Dod (3.00 e-01)	1.68518 e-01	1.40120 e-01	9.22721 e-03	1.05285 e-01	1.68222 e-02
Dod (1.00 e-01)	2.87960 e-03	2.87131 e-03	5.80985 e-06	7.53573 e-06	6.32871 e-07
Dod (1.00 e-02)	2.06189 e-06	2.06189 e-06	2.17456 e-12	2.06824 e-12	1.12133 e-14
Dod (1.00 e-03)	2.00602 e-09	2.00602 e-09	2.01614 e-18	2.00608 e-18	1.01110 e-21
Dod (1.00 e-04)	2.00060 e-12	2.00060 e-12	2.00160 e-24	2.00060 e-24	1.00110 e-28
Dod (1.00 e-05)	2.00006 e-15	2.00006 e-15	2.00016 e-30	2.00006 e-30	1.00011 e-35
Dod (1.00 e-06)	2.00001 e-18	2.00001 e-18	2.00002 e-36	2.00001 e-36	1.00001 e-42

Network ( $q_e$ )	$\sqrt{N}$ $RE(RVR) \times$	$\frac{RE(SMC)}{RE(RVR)}$	$\sqrt{N}$ $RE(Bal) \times$	$\frac{RE(SMC)}{RE(Bal)}$	$\sqrt{N}$ $RE(AZV) \times$	$\frac{RE(SMC)}{RE(AZV)}$
Arp (5.00 e-01)	1.69 e+00	3.06 e+00	1.11 e+01	4.65 e-01	1.14 e+01	4.53 e-01
Arp (3.00 e-01)	6.84 e-01	2.14 e+00	2.36 e+00	6.19 e-01	2.89 e+00	5.07 e-01
Arp (1.00 e-01)	1.27 e+00	2.42 e+00	2.01 e+00	1.53 e+00	3.24 e+00	9.50 e-01
Arp (1.00 e-02)	6.19 e+00	6.32 e+00	1.25 e+00	3.12 e+01	2.68 e+00	1.46 e+01
Arp (1.00 e-03)	2.09 e+01	1.94 e+01	1.24 e+00	3.28 e+02	9.67 e-01	4.20 e+02
Arp (1.00 e-04)	6.66 e+01	6.13 e+01	1.26 e+00	3.25 e+03	3.10 e-01	1.32 e+04
Arp (1.00 e-05)	2.11 e+02	1.94 e+02	1.26 e+00	3.24 e+04	9.82 e-02	4.16 e+05
Arp (1.00 e-06)	6.67 e+02	6.12 e+02	1.26 e+00	3.24 e+05	3.11 e-02	1.31 e+07
C6 (5.00 e-01)	1.15 e-01	3.02 e+01	3.43 e-01	1.01 e+01	1.12 e-01	3.11 e+01
C6 (3.00 e-01)	9.61 e-02	1.43 e+02	5.32 e-01	2.58 e+01	9.06 e-02	1.52 e+02
C6 (1.00 e-01)	1.78 e-02	1.25 e+04	7.53 e-01	2.96 e+02	1.71 e-02	1.31 e+04
C6 (1.00 e-02)	5.03 e-04	1.41 e+08	8.55 e-01	8.27 e+04	5.01 e-04	1.41 e+08
C6 (1.00 e-03)	1.58 e-05	1.41 e+12	8.65 e-01	2.59 e+07	1.58 e-05	1.41 e+12
C6 (1.00 e-04)	5.00 e-07	1.41 e+16	8.66 e-01	8.17 e+09	5.00 e-07	1.41 e+16
C6 (1.00 e-05)	1.89 e-08	1.18 e+20	8.66 e-01	2.58 e+12	1.89 e-08	1.18 e+20
C6 (1.00 e-06)	num. pblm.	num. pblm.	8.66 e-01	8.17 e+14	num. pblm.	num. pblm.
Dod (5.00 e-01)	4.32 e-01	3.62 e+00	2.24 e+00	6.98 e-01	1.26 e+00	1.24 e+00
Dod (3.00 e-01)	5.70 e-01	3.90 e+00	1.93 e+00	1.15 e+00	7.70 e-01	2.89 e+00
Dod (1.00 e-01)	8.37 e-01	2.22 e+01	9.53 e-01	1.95 e+01	2.76 e-01	6.74 e+01
Dod (1.00 e-02)	7.15 e-01	9.74 e+02	6.97 e-01	9.98 e+02	5.14 e-02	1.36 e+04
Dod (1.00 e-03)	7.08 e-01	3.15 e+04	7.06 e-01	3.16 e+04	1.59 e-02	1.41 e+06
Dod (1.00 e-04)	7.07 e-01	1.00 e+06	7.07 e-01	1.00 e+06	5.00 e-03	1.41 e+08
Dod (1.00 e-05)	7.07 e-01	3.16 e+07	7.07 e-01	3.16 e+07	1.58 e-03	1.41 e+10
Dod (1.00 e-06)	7.07 e-01	1.00 e+09	7.07 e-01	1.00 e+09	5.00 e-04	1.41 e+12

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# Conclusions

We have

- Standard Monte Carlo method is easy to implement, but has limitations for highly reliable networks, or when a small relative error is needed.
- To improve its efficiency, two main paths:
  - ▶ Reduce the variance per iteration
  - ▶ Reduce the computing time per iteration.
- Theoretical results establishing desirable properties for the behavior of variance reduction methods; BRE, VRE, etc.
- Only in some cases it has been possible to verify these properties.



# Conclusions

We have

- RVR does not always verify BRE;
- RVR balanced version verifies BRE;
- Zero-variance IS approximation verifies BRE, and even VRE;
- Computational results illustrate the gain that can be obtained.